

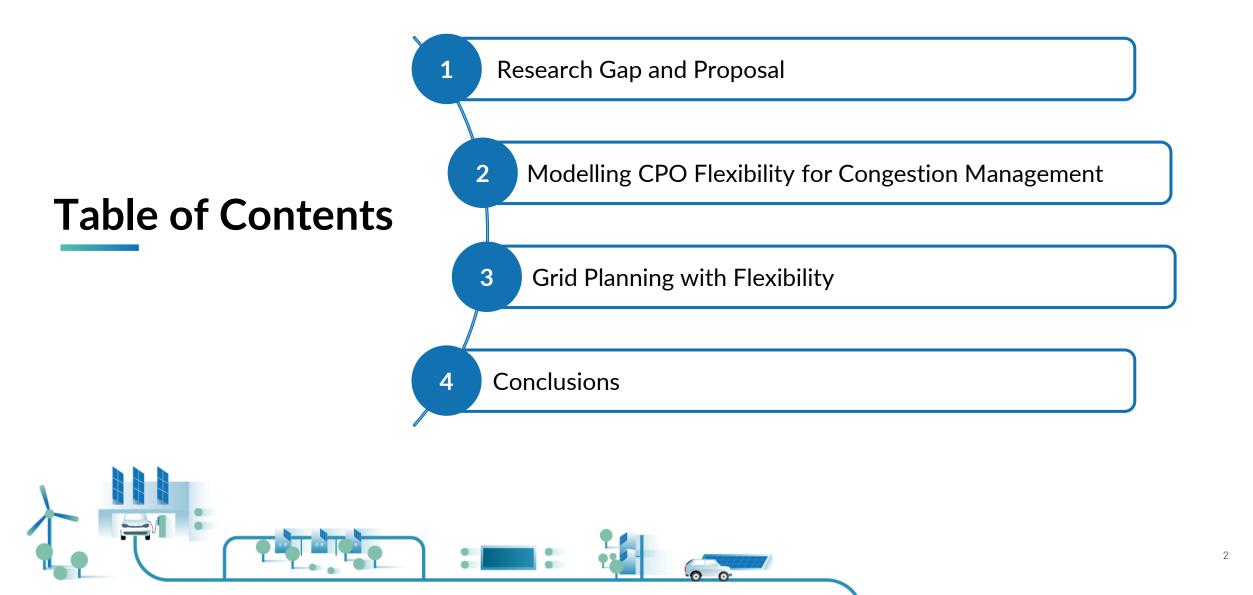


## Modeling Demand Response of Charge Point Operators to Consider Flexibility in Grid Planning

António M. Jerónimo, Pedro MS. Carvalho, Célia de Jesus, Luiz Dias, Luís Ferreira, Hugo Morais

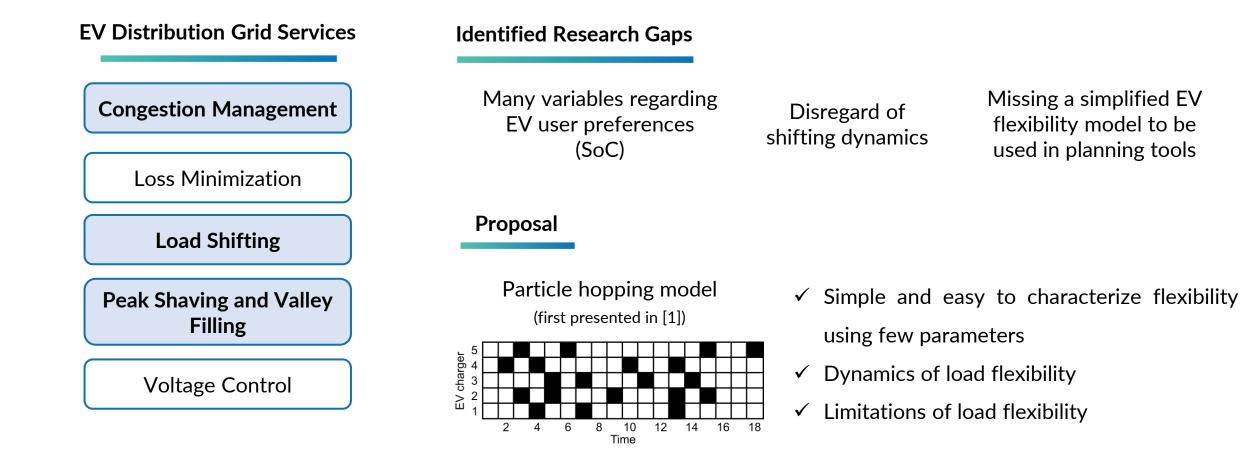






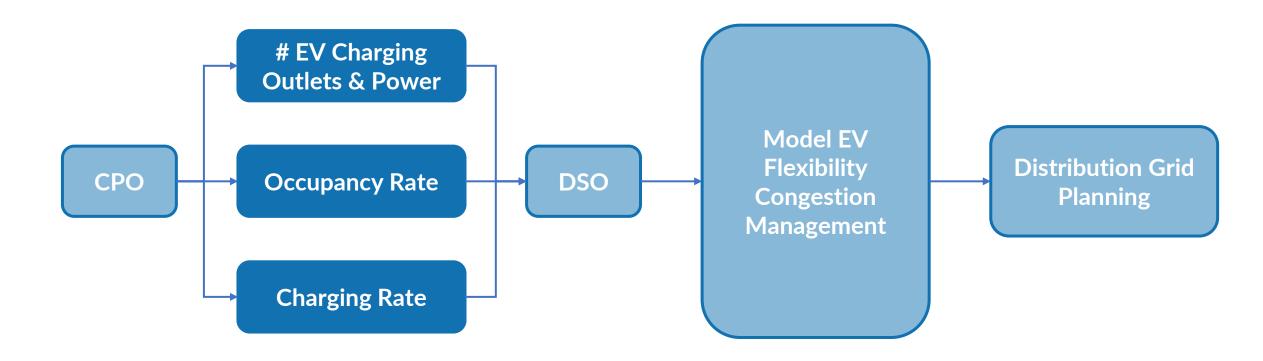
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### **Research Gap and Proposal**

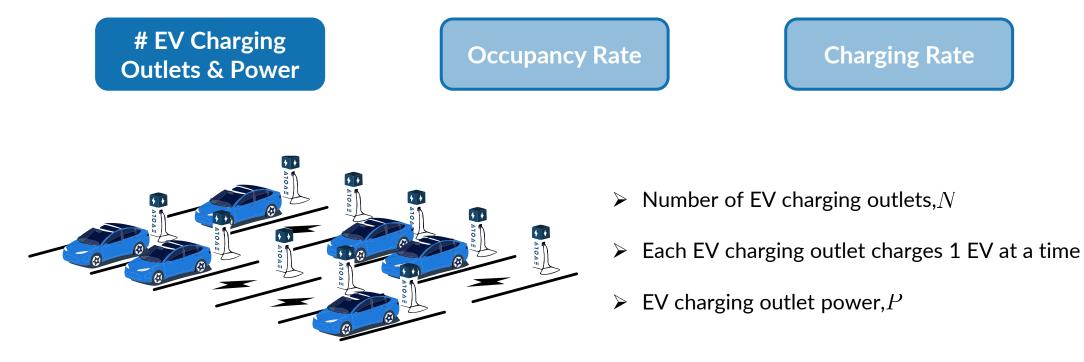


[1] Carvalho, P.M.S. and Ferreira, L.A.F.M. (2019), Intrinsic limitations of load-shifting response dynamics: preliminary results from particle hopping models of homogeneous density incompressible loads. IET Renewable Power Generation, 13: 1190-1196. https://doi.org/10.1049/iet-rpg.2018.5838

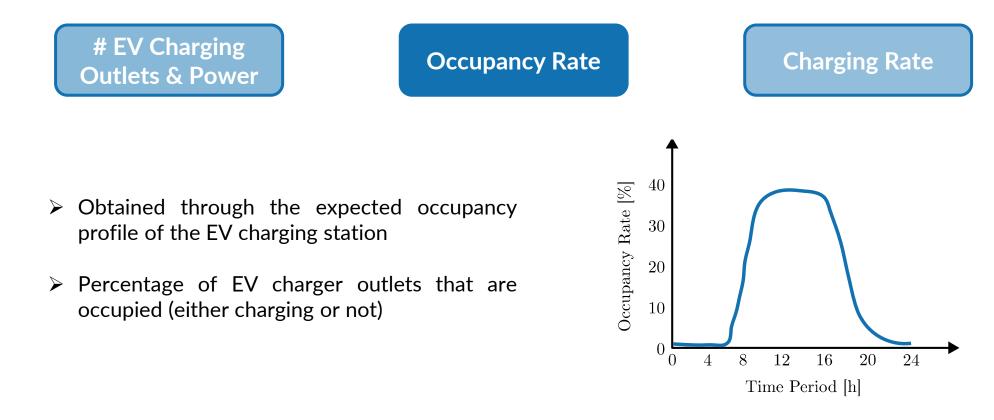






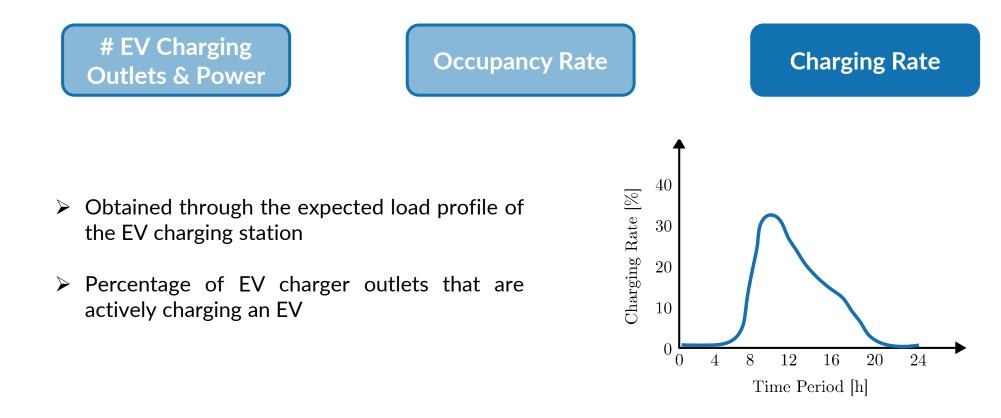






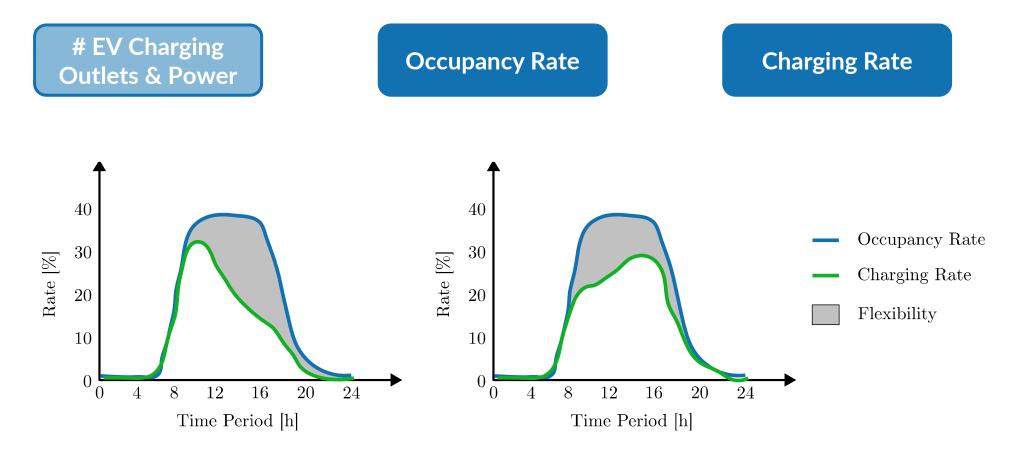
Analysis of a 52 EV parking lot located in the NASA *Jet Propulsion Laboratory* using the ACN Dataset

#### **Characterization of CPOs**



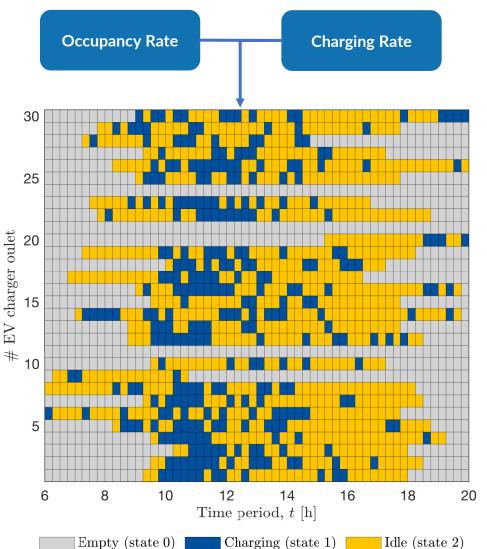
Analysis of a 52 EV parking lot located in the NASA *Jet Propulsion Laboratory* using the ACN Dataset



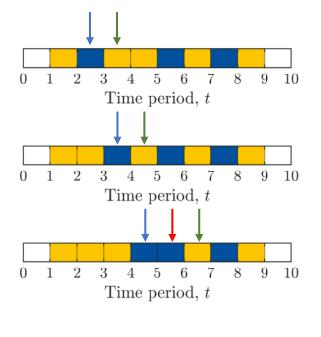


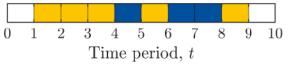
#### **Modelling CPO Shifting Flexibility**

- Particle Hopping Models
- Lattice representing the generated EV outlet charging scheduled
- Stochastic charging schedules generated using a Markov Chain
- Three states: Empty, Idle, and Charging



#### **Modelling CPO Shifting Flexibility**





- Shifting flexibility represented in the lattice by the idle position ahead of each charging particle
- Allows regulating the EV charging station power output
- Dynamic process

#### **Flexibility Evaluation of CPOs**

 $\succ$  L(t) - Aggregate (normalized) demand of EVCS at time t

$$L(t) = \sum_{n=1}^{N} x_n(t), \quad t = 1, ..., T$$
  
Load demand of the  $n^{th}$  EV outlet at time  $t$   
 $x_n(t) \in \{0,1\}, n = 1, ..., N, t = 1, ..., T$ 

- $\succ$   $L^*(t)$  Target set for the aggregate demand of the EVCS at time t
- >  $\Delta L(t)$  Changes in aggregate demand of EVCS at time t

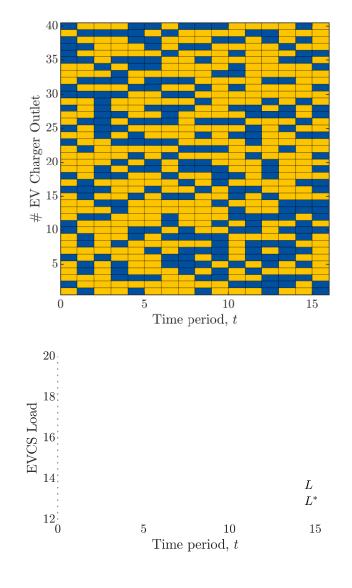
 $\Delta L(t) = L^*(t) - L(t)$ 

**Control aggregate demand?** 

Shifting charging particles

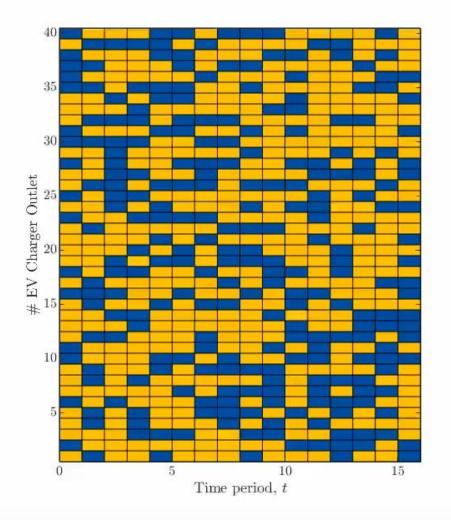
 $\blacktriangleright$  v(t) - Load particle shifting velocity (number of shift per time period) at time t

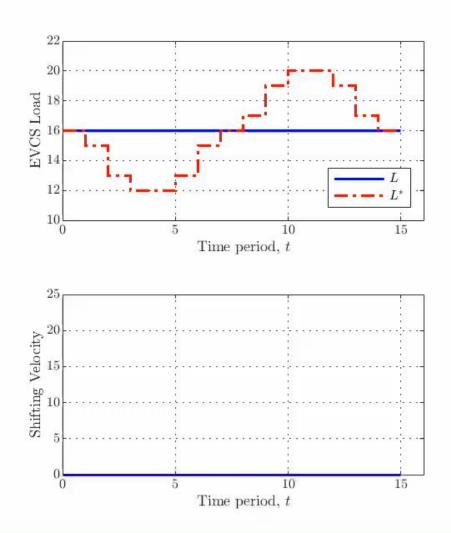
$$v(t) = \sum_{n=1}^{N} v_n(t), \quad v_n \in \{0,1\}, n = 1, \dots, N$$





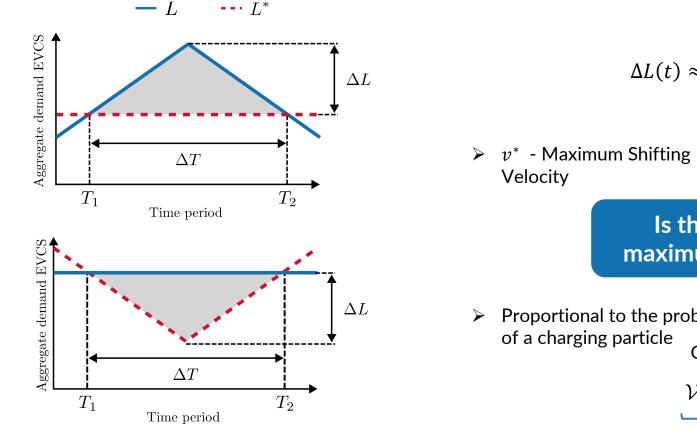
**Flexibility Evaluation of CPOs** 

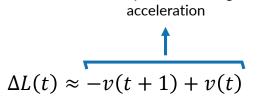




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#### **Flexibility Evaluation of CPOs**



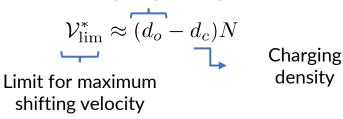


Load particle shifting

$$v^* = \frac{\Delta L \Delta T}{2}$$

Is there a limit for the maximum shifting velocity?

Proportional to the probability of having an idle particle ahead Occupancy density



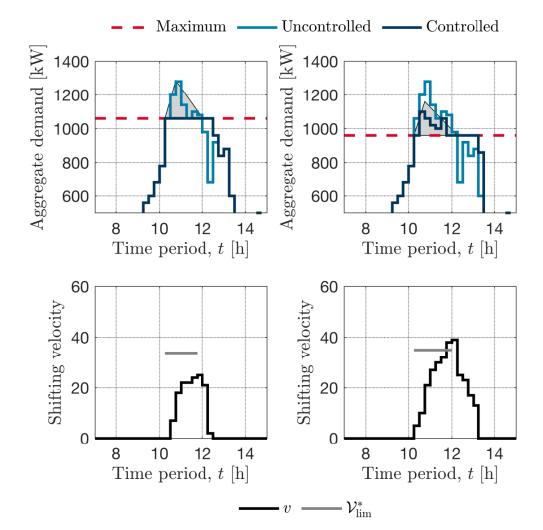
#### Flexibility Evaluation of CPOs

 Condition to be flexibility enough to follow the target

$$v^* \leq \mathcal{V}_{\lim}^*$$

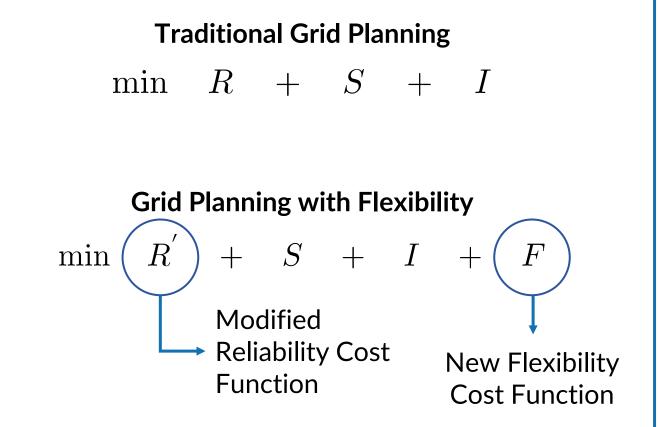
$$\Delta L \le 2 \frac{d_o - d_c}{\Delta T} N$$

Magnitude of the target function is set by the charging and occupancy densities as well as the congestion time





## **Grid Planning with Flexibility**



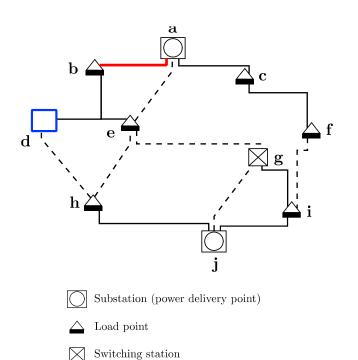
- Congestions are translated into Energy-Not-Supplied (ENS)
- Economical value for ENS is set by regulators
- Cost functions evaluated for a given planning horizon
- Minimization of corresponding costs



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## **Grid Planning with Flexibility**

#### **Flexibility Cost function**



EVCS

#### Defining:

- S Congested asset
- $\Delta L_s$  Load shed downstream congested asset
- $D_s$  Maximum Load Reduction downstream congested asset
- $N_s$  Set of flexibility resources downstream congested asset
- $\Delta T_s$  Congestion duration

#### Then:

D

$$_{g} = 2\frac{d_{o} - d_{c}}{\Delta T_{s}}N \qquad D_{s} = \min\left\{\sum_{\substack{g \in N_{s} \\ \pi_{g} < \gamma}} D_{g}, \quad \Delta L_{s}\right\}$$

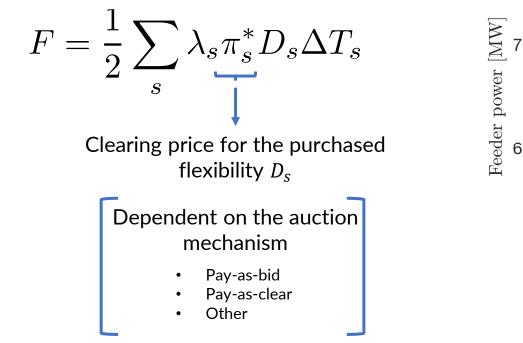
Less than marginal cost of ENS

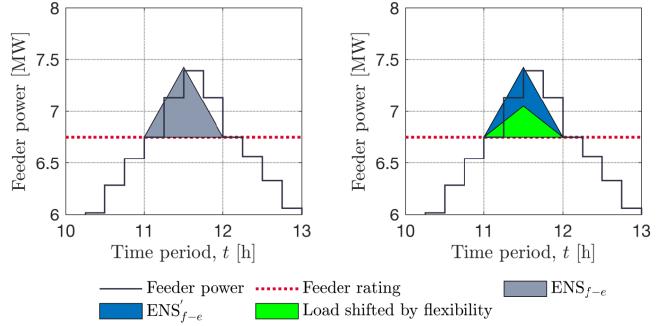
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## **Grid Planning with Flexibility**

#### **Flexibility Cost function**





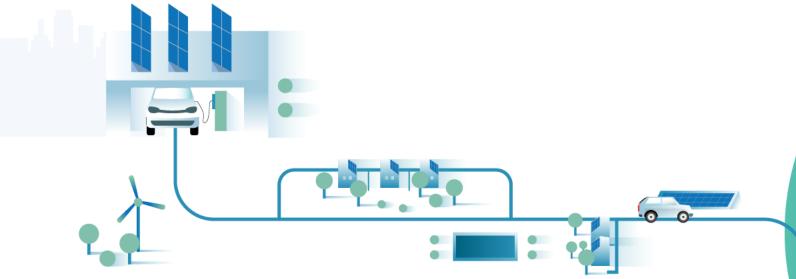


### Conclusions

- ✓ Developed an EV Charging Flexibility model that considers dynamics and limitations of load shifting
- ✓ CPOs characterized by their charging and occupancy rates
- ✓ Definition of a new flexibility cost function to be traded off again reliability, energylosses and investment costs
- ✓ This methodology allows finding hybrid solutions where both flexibility and reinforcement strategies are employed



## Thank you! Questions?







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